

# INTEGRATING INFERENCE AND EXPERIMENTAL DESIGN FOR CONTEXTUAL BEHAVIORAL MODEL LEARNING

Gongtao Zhou Haoran Yu  
zhought3@qq.com, yhrhawk@gmail.com

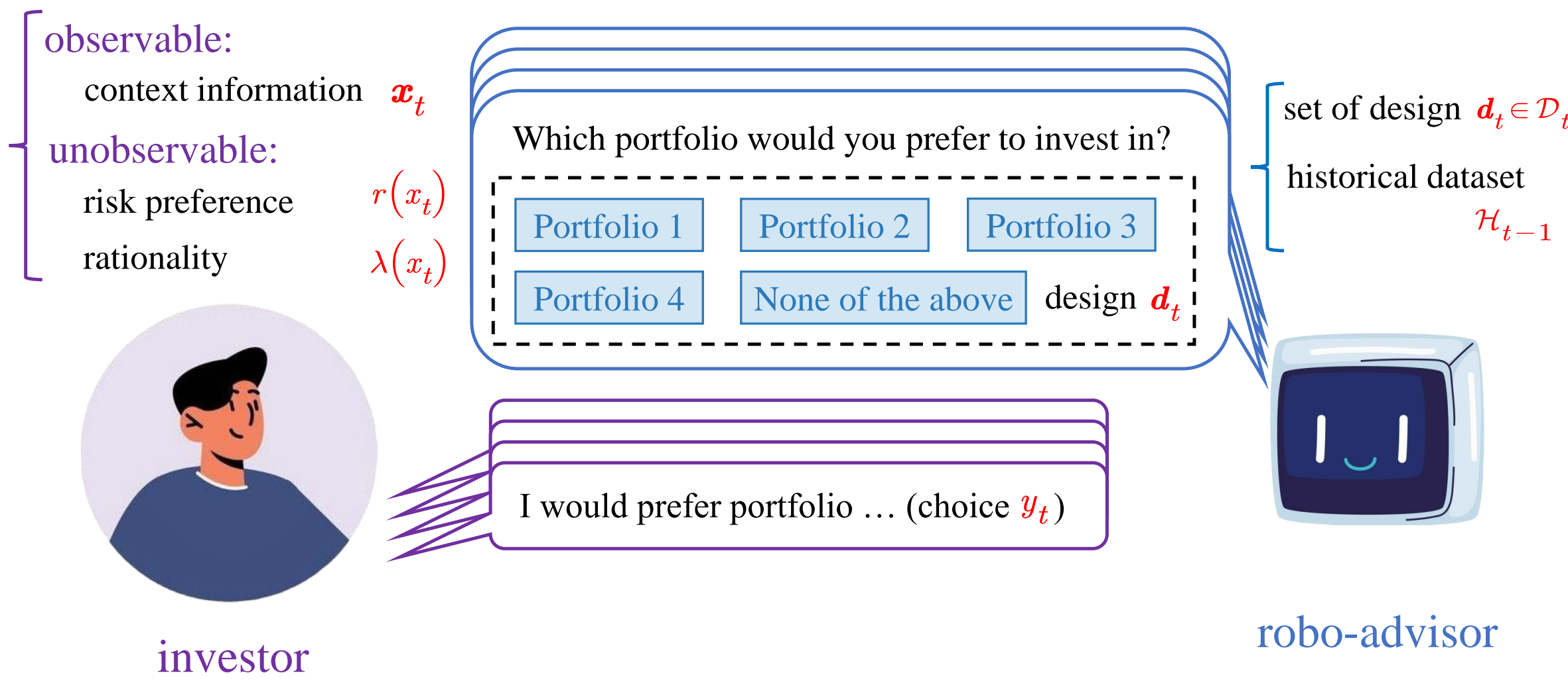
School of Computer Science & Technology, Beijing Institute of Technology



## BACKGROUND

### Portfolio Choice:

- Trading platforms utilize robo-advisors to interact with investors and elicit hidden information from their choices across portfolios.



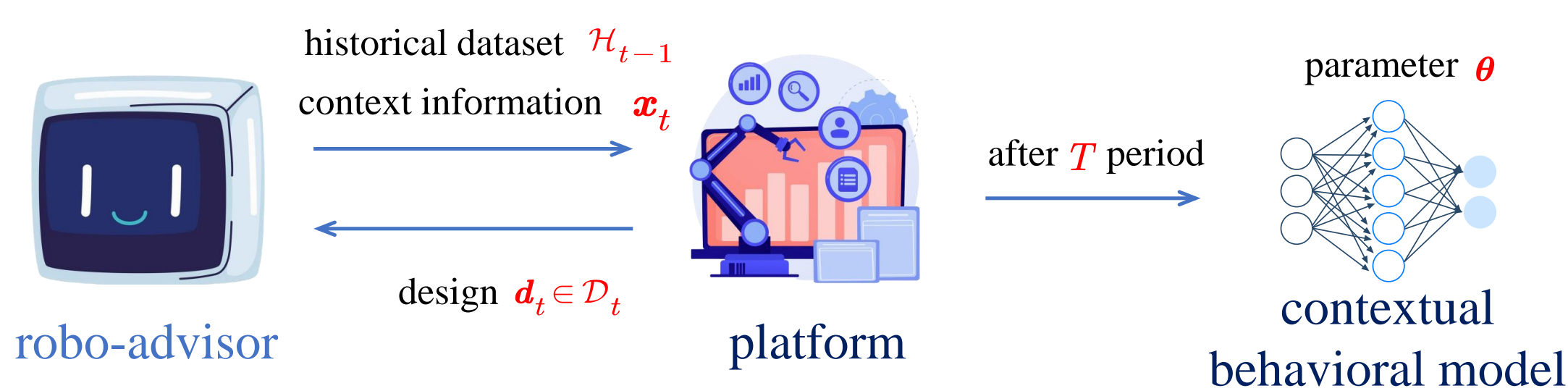
- Inferring the relationship between an investor's observable and hidden information depends on the platform's experimental design.

**Our Goal:** Design experiment to learn contextual behavioral model.

- Collect the most informative data for learning network weights.

## PROBLEM FORMULATION

- The platform strategy is based on:
  - $t$ : period of platform interaction  $t = 1, 2, \dots, T$
  - $\mathbf{x}_t$ : investor contextual information
  - $\mathbf{d} = \{(m_1, v_1), \dots, (m_K, v_K)\}$ : designed investment portfolios
    - $m, v$ : return mean and return variance
    - $K$ : the number of portfolios in design
  - $\mathcal{H}_{t-1} \triangleq \{(\mathbf{x}_1, \mathbf{d}_1, y_1), \dots, (\mathbf{x}_{t-1}, \mathbf{d}_{t-1}, y_{t-1})\}$ : historical dataset
  - $\theta$ : contextual behavioral model weights



### Platform's Experimental Design Problem

Given  $\mathcal{H}_{t-1}$  and  $\mathbf{x}_t$ , how to optimize the design  $\mathbf{d}_t \in \mathcal{D}_t$  for training an accurate  $\theta$ -parameterized neural network?

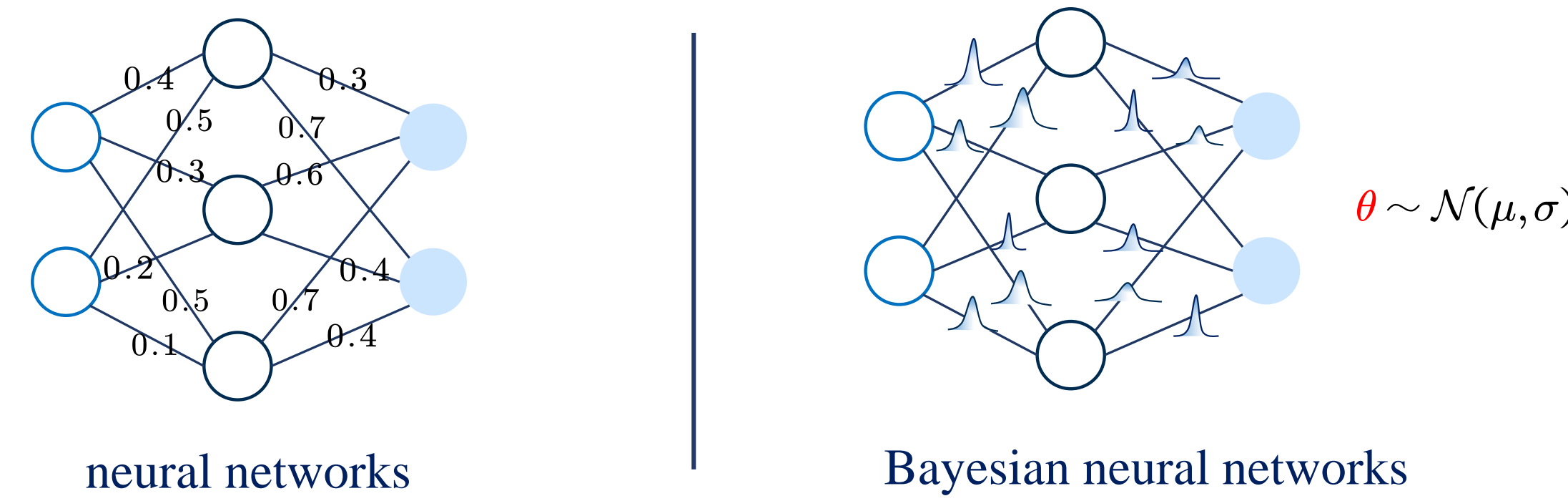
## PLATFORM'S EXPERIMENTAL DESIGN SOLUTION

- Expected information gain (EIG):** quantify design quality

$$\text{EIG}(\mathbf{d}) \triangleq \mathbb{E}_{p(y|\mathbf{x}, \mathbf{d})} [H[p(\theta)] - H[p(\theta|\mathbf{x}, y, \mathbf{d})]]$$

- $p(\theta)$  is prior;  $p(\theta|\mathbf{x}, y, \mathbf{d})$  is posterior.
- The uncertainty of  $\theta$  decreases as new data is collected.

- Bayesian neural networks (BNN):** calculate EIG



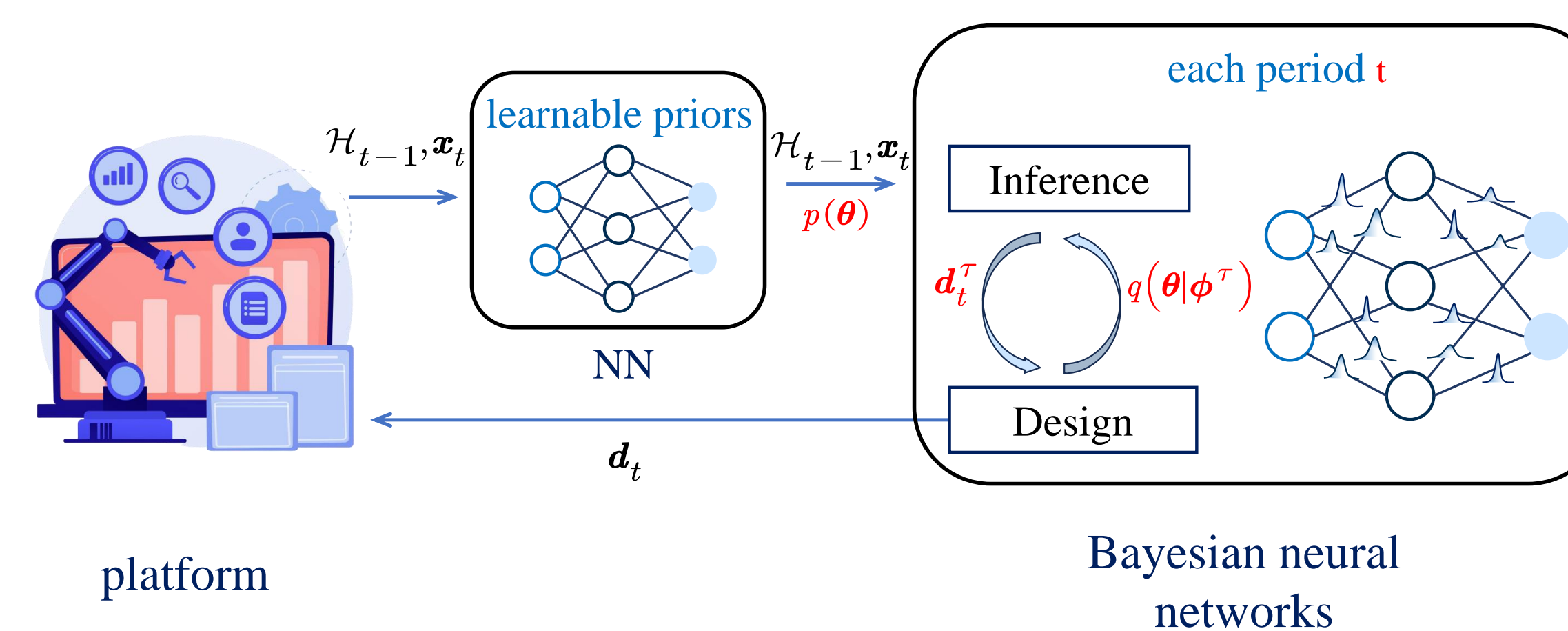
- EIG calculations necessitate non-fixed model weights.
- We use variational inference  $q(\theta|\phi)$  to approximate  $p(\theta|\mathbf{x}, y, \mathbf{d})$ .

### Our Solution:

- Inference:** learn  $\phi$  by training Bayesian neural network
- Design:** choose the design to maximize the estimated EIG

## I-ID-LP

- Integrated Inference-and-Design with Learnable Priors (I-ID-LP)**
  - Learnable prior:** a random initialized prior distribution  $p(\theta)$  will disrupt the inference step during the early periods
  - Integrated Inference-and-Design:** separating inference and design may lead to suboptimal performance, as the optimization of  $\phi$  fails to maximize information gain



## ITERATIVE OPTIMIZATION

### Loss function for iterative optimization:

- Optimize  $\phi^\tau$  while keeping  $\mathbf{d}_t = \mathbf{d}_t^{\tau-1}$ :

$$\phi^\tau = \arg \min_{\phi} \text{KL}[q(\theta|\phi) || p(\theta|\mathcal{H}_{t-1})] - \mathbb{E}_{q(\theta|\phi)} [\log \text{KL}[p(y_t|\mathbf{x}_t, \mathbf{d}_t^{\tau-1}, \theta) || p(y_t|\mathbf{x}_t, \mathbf{d}_t^{\tau-1})]]$$

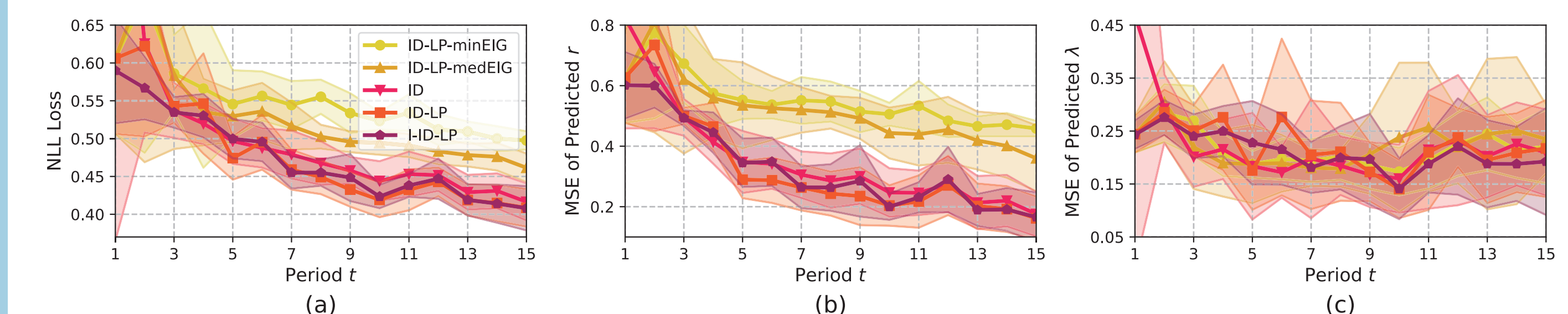
- Optimize  $\mathbf{d}_t^\tau$  while keeping  $\phi = \phi^\tau$ :

$$\mathbf{d}_t^\tau = \arg \max_{\mathbf{d}_t} \int q(\theta|\phi^\tau) \log \text{KL}[p(y_t|\mathbf{x}_t, \mathbf{d}_t, \theta) || p(y_t|\mathbf{x}_t, \mathbf{d}_t)] d\theta$$

## EXPERIMENTS & RESULTS

### Comparison Among ID Methods:

- NLL Loss:** the loss of predicting investor choice  $y$  in  $\mathcal{H}_{test}$ .
- MSEs of Predicting  $r(\mathbf{x})$  and  $\lambda(\mathbf{x})$ :** the mean squared errors between the outputs of NN and the actual  $r(\mathbf{x})$ ,  $\lambda(\mathbf{x})$  of investors in  $\mathcal{H}_{test}$ .



Comparison of ID Methods Under Setting A

### Comparison with Other Methods

Table: Negative Log-Likelihood Loss on Testing Dataset

Method	Setting A	Setting B	Setting C
<b>ID</b>	0.416 ± 0.025	0.319 ± 0.017	0.397 ± 0.010
<b>ID-LP</b>	0.409 ± 0.025	0.306 ± 0.018	0.390 ± 0.007
<b>I-ID-LP</b>	<b>0.408 ± 0.029</b>	<b>0.297 ± 0.010</b>	<b>0.387 ± 0.007</b>
<b>ID-LP-minEIG</b>	0.498 ± 0.012	0.427 ± 0.026	0.565 ± 0.113
<b>ID-LP-medEIG</b>	0.461 ± 0.019	0.331 ± 0.010	0.435 ± 0.047
<b>PreEntropy</b>	0.557 ± 0.111	0.366 ± 0.028	0.634 ± 0.216
<b>MinMaxPro</b>	0.611 ± 0.122	0.366 ± 0.030	0.705 ± 0.196
<b>LaplaceInfer</b>	0.462 ± 0.026	0.327 ± 0.012	0.411 ± 0.013
<b>Random</b>	0.459 ± 0.022	0.329 ± 0.012	0.425 ± 0.035
<b>MaxMean</b>	0.468 ± 0.003	0.404 ± 0.045	0.510 ± 0.012
<b>MaxVar</b>	0.560 ± 0.008	0.340 ± 0.008	0.624 ± 0.010
<b>MaxMean+Var</b>	0.468 ± 0.003	0.336 ± 0.004	0.501 ± 0.003
<b>MaxMean-Var</b>	0.512 ± 0.013	0.803 ± 0.424	0.562 ± 0.063

More results on other experiments can be found in our paper.